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Third, since the drive system is so constituted that the electric rotary machine is driven by the engine, an inertia torque of the rotor of the electric rotary machine is exerted on the engine side as a load. Thus, during running under the engine drive, in order to correctly execute an acceleration command from the driver, it is necessary to generate an additional torque for canceling the inertia torque in the engine side as well as the torque corresponding to the acceleration command. This poses a problem that the specific fuel consumption is deteriorated in order to improve a driving performance.

Accordingly, an object of the present invention is to improve a transmission efficiency, reduce a specific fuel consumption of a vehicle and make a drive system compact, in a power transmission apparatus constituted by a gear change mechanism having an electric rotary machine and a clutch mechanism.

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BRIEF DESCRIPTION OF THE DRAWINGS

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which shows a torque transmission course when running by an engine driving force;

Fig. 3 is the driving system shown in Fig. 1, which shows a torque transmission course during a gear change operation;

Fig. 4 is the driving system shown in Fig. 1, which shows a torque transmission course after the gear change operation;

Fig. 5 is a schematic view of a drive system of a motor vehicle according to a second embodiment of the invention;

Fig. 6 is a schematic view of a drive system of a motor vehicle according to a third embodiment of the invention;

Fig. 7 is a schematic view of a transmission of a front engine front drive vehicle (FF vehicles) to which the invention is applied;

Fig. 8 is a schematic view of another transmission of the FF vehicles to which the invention is applied;

Fig. 9 is a schematic view showing a control system of a hybrid motor vehicle to which the invention is applied;

Fig. 10 is a schematic view of a hybrid motor vehicle in which a transmission according to the invention is provided in a front wheel side; and

Fig. 11 is a schematic view of a drive system of motor vehicles according to a fourth embodiment of

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DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS OF THE
PRESENT INVENTION

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an "ON/OFF" operation is of such a type that an operation force of a clutch pedal (not shown) is transmitted by a hydraulic actuator or the like. The start clutch 3 may be also those conventionally known, such as a wet type multi-plate clutch, an electro-magnetic clutch and so on.

sub a12 Reference numerals 14 denote a high speed multi-plate clutch which has a function of engaging and disengaging with and from the high speed driven gear 15 under an operation of a hydraulic actuator 24. Here, when the high speed multi-plate clutch 14 is gradually pressed by the hydraulic actuator 24, the torque of the transmission input shaft 4 is gradually transmitted to the transmission output shaft 19. A rotational speed of the transmission output shaft 19 can be controlled with relation to a load (a road status, a weight of vehicle body, etc.) by controlling a force for pressing the high speed multi-plate clutch 14 by means of the hydraulic actuator 24. In this case, a torque of the engine 1 is transmitted along a transmission course from the engine output shaft 2 to the transmission output shaft 19 successively through the start clutch 3, the transmission input shaft 4, the high speed drive gear 5, the high speed multi-plate clutch 14 and the high speed driven gear 15 (see Fig. 3).

Next, referring to Table 1, a description will be given of a basic processing method for controlling the engine 1 and the motor generator 11 in respective

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operating modes. Here, with respect to the gear change
dog clutch 17, a state that it engages with the low
speed driven gear 16 is defined as a 1st position, a
state that it engages with the middle speed driven gear
5 18 is defined as a 2nd position, and an "OFF" state
thereof is defined as an N (neutral) position.

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Table 1 Explanation of Operation Modes

No.	Mode	Operation State	Start Clutch	High Speed Multi-Plate Clutch	Gear change Dog Clutch	MG Dog Clutch	Notes
1	Stop	Idling power Generation	ON	OFF	N	ON	Engine Start
2		Idling stop	OFF	OFF	1 st	ON	
3	M/G Running	Reverse	OFF	OFF	1 st	ON	Negative Rotation
4		Low Vehicle Speed (First Speed)	OFF	OFF	1 st	ON	Regeneration Brake
5		Middle Vehicle Speed (Second Speed)	OFF	OFF	2 nd	ON	
6		High Vehicle Speed (Third Speed)	OFF	ON	N	ON	
7	Engine Running	Low Vehicle Speed (First Speed)	ON	OFF	1 st	OFF	Assist, Power Generation and Regeneration
8			ON	OFF	1 st	ON	
9		Middle Vehicle Speed (Second Speed)	ON	OFF	2 nd	OFF	
10			ON	OFF	2 nd	ON	Assist, Power Generation and Regeneration
11		High Vehicle Speed (Third Speed)	ON	ON	N	OFF	Assist, Power Generation and Regeneration
12			ON	ON	N	ON	

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AB First, a description will be given of a control method in the stop mode. At a time of idling power generation (No. 1 in Table 1), the start clutch 3 is set to "ON", the high speed multi-plate clutch 14 is set to "OFF", the gear change dog clutch 17 is set to the N (neutral) position, and the motor generator dog clutch 9 is set to "ON". Accordingly, the torque from the engine 1 is transmitted to the motor generator 11 via the middle speed drive gear 7 and the motor generator driven gear 8, and it is possible to generate power while idling the engine 1 in a state that the vehicle stops. Further, in order to realize a smooth start from this state, it is necessary to start the vehicle while slipping the high speed multi-plate clutch 14. After starting, the high speed multi-plate clutch 14 is quickly disengaged, the transmission input shaft 4 and the transmission output shaft 19 are synchronously rotated by using the motor generator 11, an electronically controlled throttle 22 and the like, and the gear change dog clutch 17 is set to the 1st position. At this time, in the case that the gear change ratio of a gear stage having the multi-plate clutch arranged is small, there is a risk that the engine stops without starting. In this case, the engine is prevented from stopping at a time of starting by increasing the torque of the motor generator 11. Further, as another starting method, there is a method of first setting the start clutch 3 to "OFF", thereafter controlling the motor generator 11 so as to synchronously rotate the transmission input shaft 4 and the transmission output shaft 19, engaging the gear

a13 change dog clutch 17 with the 1st position, and starting to the torque of the engine 1 while slipping the start clutch 3 as conventionally known or starting by the motor generator 11.

5 ^{sub a14} Next, a description will be given of a control method at a time of idling stop (No. 2). The idling stop can be performed by setting the start clutch to "OFF" from the state of the idling power generation (No. 1) and stopping a fuel supply to the engine 1. At this
10 time, it is necessary to set the gear change dog clutch 17 to the 1st position for realizing a smooth start from the idling stop. When starting, it is possible to employ a method of starting according to the torque of the motor generator 11 and a method of starting
15 according to the torque of the motor generator 11 and push-starting the engine 1. In the case of push-starting the engine 1, it is necessary to control the rotational speed of the engine 1 within a range capable of starting while slipping the start clutch 3. Further,
20 in the case of push-start, it is significantly effective to utilize an engine with electromagnetic drive type intake and exhaust valves. In the conventional type of engine in which the intake and exhaust valves are opened and closed by rotating a cam shaft, there is a cylinder
25 at which the intake and exhaust valves are closed when the engine stops and this generates a great load, so that it is necessary that the motor generator 11 generates a great torque when push-starting. On the

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Further, the structure may be made such as to start by the torque of the motor generator 11 according to a conventionally known starter motor (a dotted line 300 in Fig. 1) disposed in the engine side and start engine 1 by the starter motor so as to gradually engage the start clutch and add the torque of the engine 1, thereby running.

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a/b* Next, a description will be given of a travel by the motor generator 11. When reversing (No. 3), the start clutch 3 is set to "OFF", the motor generator dog clutch 9 is set to "ON", and any one of the low speed driven gear 16, the middle speed driven gear 18 and the high speed driven gear 15 is selected so as to rotate the motor generator 11 in a negative direction (a forward direction of the vehicle is set to a positive direction and a backward direction is set to a negative direction), thereby running. It has been known that a great drive torque is required when reversing, the gear change dog clutch 17 may be set to the 1st position and the high speed multi-plate clutch 14 may be set to "OFF". Further, at a time of backward moving, the

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second speed drive state).

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The start clutch 3 is set to "ON", the high speed multi-plate clutch 14 is set to "OFF", the gear change dog clutch 17 is set to the 2nd position, and the motor generator dog clutch 9 is set to "OFF" (No. 9). At this time, it is possible to run at middle vehicle speed by the engine 1. Further, the start clutch 3 is set to "ON", the high speed multi-plate clutch 14 is set to "OFF", the gear change dog clutch is set to the 2nd position, and the motor generator dog clutch 9 is set to "ON" (No. 10). In the same manner as that at the low vehicle speed time, in the case that a residual capacity of the battery 13 is a little and a necessity of generating power by driving the motor generator 11 by means of the engine 1 is generated, running by the engine 1 and the power generation by the motor generator 11 can be performed. Further, in the case that the battery 13 is fully charged and has the residual capacity in reserve, a torque assist can be performed by the motor generator 11, and running can be performed by the engine 1 and the motor generator 11. Further, in the drive motor No. 10 mentioned above, since the motor generator 11 is directly connected to the transmission output shaft 19, an energy can be regenerated when reducing the speed.

Next, a description will be given of running by the engine 1 at the high vehicle speed time (in the third speed drive state).

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25 Further, at a time of running by the engine 1 mentioned above, in the case that the power generation and the torque assist by the motor generator 11, it is necessary to control the motor generator 11 so as to

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Fig. 2 is a schematic view in the case of accelerating the vehicle in a state of running by the drive force of the engine. A dotted thick line in Fig. 2 shows a transmission course of the torque. As an example, a case of engaging the start clutch 3 and engaging the gear change dog clutch 17 with the low speed driven gear 16 is supposed. At this time, the torque of the engine 1 is transmitted to the transmission output shaft 19 via the low speed drive gear 6 and the low speed driven gear 16. Here, in the case of accelerating the vehicle, since the motor generator 11 is intercepted from the transmission input shaft 4 by the motor generator dog clutch 9 and the inertia torque of the motor generator 11 can be reduced, it is not necessary to increase the torque of the engine 1 and the specific fuel consumption can be reduced at a time of acceleration.

Figs. 3 and 4 are schematic views in the case of changing speed from the first speed drive state in Fig. 3 to the second speed drive state. When the vehicle speed becomes in the gear change state, the gear change dog clutch 17 is made in the disengaged state so as to disengage a connection between the low speed driven gear and the transmission output shaft 19 as

shown in Fig. 4. At the same time, the torque of the engine 1 is transmitted to the transmission output shaft 19 via the high speed driven gear 15 by controlling the hydraulic actuator 24 so as to press the high speed multi-plate clutch 14. The torque of the engine 1 is transmitted to the wheel axle 23 due to the pressing force of the high speed multi-plate clutch 14 so as to become a drive torque for the vehicle, and the rotational speed of the engine 1 is reduced due to the increased load of the engine 1 because the gear change ratio is reduced by the high speed driven gear, so that the gear change ratio between the transmission output shaft 19 and the transmission input shaft 4 becomes close to the gear change ratio of the second speed from the gear change ratio of the first speed (in the direction of becoming small). At this time, the torque of the engine 1 is transmitted according to a transmission course from the engine output shaft 2 to the transmission output shaft 19 successively through the start clutch 3, the transmission input shaft 4, the high speed drive gear 5, the high speed multi-plate clutch 14 and the high speed driven gear 15. Here, when the gear change ratio between the transmission input shaft 4 and the transmission output shaft 19 becomes the gear change ratio of the second speed, the gear change dog clutch 17 engages with the middle speed driven gear 18 so as to engage the middle speed driven gear 18 with the transmission output shaft 19 as shown in Fig. 4.

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As mentioned above, the first speed is disengaged at a time of gear change so as to become the neutral state, however, at this time, since the torque of the engine 1 is transmitted to the wheel axle 23 by the high speed multi-plate clutch 14, the high speed drive gear 5 and the high speed driven gear 15, it is not necessary that the driver returns the acceleration pedal (that is, it is not necessary that the torque and the rotational speed of the engine 1 are adjusted). According to this structure, it is possible to change speed of the gear transmission while accelerating the vehicle. On the contrary, in the case that the driver returns the acceleration pedal and controls the electronically controlled throttle 22 so as to narrow the throttle during the driving, a rotational synchronization between the transmission input shaft 4 and the transmission output shaft 19 by the high speed multi-plate clutch 14 becomes early (the rotational

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Q2 speed of the engine 1 is early reduced), so that it is possible to shorten a time for changing the speed.

In the case of changing the speed to the third speed, it is possible to achieve the gear change by controlling the hydraulic actuator 24 so as to make the pressing force of the high speed multi-plate clutch 14 maximum and making the gear change dog clutch 17 in a disengaged state (neutral). Here, in the case of increasing the gear change ratio (shift down), the hydraulic actuator 24 may be controlled so as to obtain a target gear change ratio in a state in Fig. 3, whereby the pressing force of the high speed multi-plate clutch 14 may be adjusted. Further, the control method during the gear change mentioned above can be realized in running mode by the motor generator 11, the mode of running by the engine 1 and generating power by the motor generator 11, and running mode by the engine 1 and the motor generator 11, in addition to running mode by the engine 1 as shown in the embodiment.

Q23 Fig. 5 is a schematic view of a whole of an automobile system according to a second embodiment of the invention. This system corresponds to a structure in which a motor generator dog clutch 9 is arranged in a side of the transmission input shaft 4 and a middle speed drive gear 7b is accordingly arranged so as to freely rotate with respect to the transmission input shaft 4, in the structure shown in Fig. 1. Further, a motor generator driven gear 8b is fixed to the motor

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generator output shaft 10. The other structures are the same as those shown in Fig. 1, the same reference numerals as those in Fig. 1 are provided to the same elements in Fig. 5, and a description thereof will be omitted. Further, when employing the structure, there is a disadvantage that the motor generator 11 is rotated in an accompanying manner when running according to the engine 1 in the drive mode No. 9 shown in Table 1, however, it is possible to disengage the motor generator 11 when running according to the engine 1 in the other drive modes, and since the inertia torque of the motor generator 11 can be reduced in the case of accelerating the vehicle, it is not necessary to increase the torque of the engine 1, whereby the specific fuel consumption can be reduced when accelerating.

Fig. 6 is a schematic view of a whole of an automobile system according to a third embodiment of the invention. This system corresponds to a structure in which a low speed multi-plate clutch 27 and a middle speed multi-plate clutch 17c are respectively arranged with respect to the low speed driven gear 16 and the middle speed driven gear 18 in place of the gear change dog clutch 17 and a motor generator multi-plate clutch 9c is arranged in place of the motor generator dog clutch 9, in the structure shown in Fig. 1. Also in this structure, it is possible to realize the same effect as the effect of engaging and disengaging the gear change dog clutch 17 and the motor generator dog

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5 transmission output shaft 19 are connected so as to become in the same state as the state of setting the gear change dog clutch 17 to the 1st position in Fig. 1.

15 Further, when controlling the low speed hydraulic actuator 25 and the middle speed hydraulic actuator 26 so as to release the pressing force of the low speed multi-plate clutch 27 and the middle speed multi-plate clutch 17c, the structure becomes in the same state as the state of setting the gear change dog clutch 17 to the N (neutral) position in Fig. 1. In the same manner, when controlling the motor generator hydraulic actuator 28 so as to adjust the pressing force of the motor generator multi-plate clutch 9c maximum, 25 the state of turning on and off the motor generator dog clutch 9 can be realized. The other structures are the same as the structures shown in Fig. 1, the same reference numerals as those in Fig. 1 are attached to

the same elements in Fig. 6, and a description thereof will be omitted.

Sub 924 Fig. 7 is a schematic view of a transmission for a front engine front drive vehicle (an FF vehicle) to which the present invention is applied. A transmission input shaft 804 and a transmission output shaft 819 are arranged in an inner portion of a housing 850 so as to be in parallel to each other and freely rotate. The housing 850 is constituted by a substantially cylindrical main body portion 862, a clutch housing 851 and a differential gear housing 854 which are integrally formed, a front portion 863 mounted to a front end side of the main body portion 862 and an extension portion 864 mounted to a rear end side of the main body portion 862. A supporting portion 865 extending to a center side from an inner peripheral surface is formed in a rear end side of the main body portion 862, a partition wall portion 853 is formed in the front portion 863, the transmission input shaft 804 extends through the partition wall portion 853, and one end portion thereof extends to a bearing 852 mounted to a rear end side of the extension portion 864, whereby the transmission input shaft 804 is rotatably supported via the partition wall portion 853 and the bearing 852. A start clutch 803 is mounted to an end portion protruding into the clutch housing 851 of the transmission input shaft 804, and the transmission input shaft 804 is connected to an engine output shaft 802 via the start

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clutch 803. On the contrary, the transmission output shaft 819 is rotatably supported to bearings 852 respectively mounted to the partition wall portion 853 and a supporting portion 865. Further, a motor generator output shaft 810 is arranged on the same axis as the transmission output shaft 819. The motor generator shaft 810 is rotatably held by the bearings 852 respectively arranged in the supporting portion 865 and an inner surface of the extension portion 864. A motor generator 811 is installed within the extension portion 864, and a motor generator output shaft 810 is integrally formed with a rotor 860 thereof.

Further, a motor generator driven gear 808 is integrally mounted to the motor generator output shaft 810, and a motor generator drive gear 861 always engaging with the motor generator driven gear 808 is rotatably arranged on the same axis as the transmission input shaft 804. Reference numerals 809 denote a motor generator dog clutch, and has a function of engaging or disengaging the motor generator drive gear 861 with respect to the transmission input shaft 804. The differential gear housing 854 is formed in an outer side in a radial direction of the clutch housing 851 mentioned above, a differential gear carrier 858 holding a pinion 857 and a pair of right and left side gears 866 engaging with the pinion 857 are provided in an inner portion thereof, and a ring gear 856 is integrally mounted to the differential gear carrier 858. Then, a

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motor generator driven gear 908. Further, a high speed driven gear 905 and a transmission output shaft 919 are connected by pressing a high speed multi-plate clutch 914. At this time, a torque from the transmission input shaft 904 is transmitted according to a transmission course from the transmission input shaft 904 to the transmission output shaft 919 successively through the high speed drive gear 915, the high speed driven gear 905 and the high speed multi-plate clutch 914. Since the other structures are the same as those in Fig. 8, a description thereof will be omitted.

Fig. 9 is a schematic view showing a control device of a hybrid vehicle employing the Transmission shown in Fig. 7. Reference numerals 2000 in Fig. 9 denote driver's intention detecting means. The driver's intention detecting means normally corresponds to an acceleration pedal, a brake pedal and a shift lever. Reference numerals 1001 denote an engine, in the engine 1001, an amount of intake air is controlled by an electronically controlled throttle 1022 provided in an intake pipe (not shown), and an amount of fuel corresponding to the amount of air is injected from a fuel injection apparatus (not shown). Further, an ignition timing is determined from signals such as an air-fuel ratio, an engine rotational speed or the like determined by the amount of air and the amount of fuel. Reference numerals 2002 denote an engine control device. The engine control device 2002 is an apparatus for

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1009 a motor generator dog clutch. In the power train control device 2001, a target start clutch position is calculated so as to be transmitted to a start clutch control device 2003 by communicating means, whereby the start clutch 1003 is controlled. In the same manner, the high speed multi-plate clutch 1014 is controlled by a multi-plate clutch control device 2005, and the gear change dog clutch 1017 and the motor generator dog clutch 1009 are controlled by a dog clutch control device 2006.

Sub 929 Fig. 10 is an idiomatic view of a hybrid vehicle in which the Transmission shown in Fig. 7 is provided in a front wheel side. As shown in Fig. 10, it is possible to mount the Transmission to the automobile without adding the motor generator to the drive wheel side (for example, in a rear wheel side).

Fig. 11 is a schematic view of a system (a fourth embodiment of the present invention) in which a motor 300 is added between the engine 1 and the start clutch 3 in the Transmission shown in Fig. 1 and the high speed multi-plate clutch is arranged in a side of the transmission input shaft. The motor 300 is used for starting the engine 1 and driven by the engine 1 so as to generate power. Further, when reducing speed, the start clutch 3 is set to "ON" so as to regenerate. Further, in the case that the residual capacity of the battery is sufficient, the motor 300 can be used for assisting torque, whereby a great drive force can be

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As will be apparent from the above, according to the invention, the following technical advantages can be obtained:

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from the electric rotary machine as occasion demands and prevent the inertia torque of the electric rotary machine from applying to the engine side as a load.

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